

## 17) Parameter group A00: PID controller parameter

### Integrated PID-controller

An integrated PID-controller is available on standard E2000+ inverters. It is suitable for simple closed loop control projects. Specific pump control algorithm allow constant pressure control of single pumps and dual pump booster stations. Cascade control and master slave control with automatic interchange functions are available as well

|                                      |   |                    |
|--------------------------------------|---|--------------------|
| <b>FA00</b> Controller configuration | Selection: 0: closed loop control – single pump control<br>1: Master/Slave Mode<br>2: Master/Slave with interchange | Default setting: 0 |
|--------------------------------------|---|--------------------|

**FA00=0:** Suitable for standard closed loop control projects (single pump pressure control).

**FA00=1:** Dual pump cascade mode control, master pump with variable speed, slave pump fixed speed (direct grid connected)

**FA00=2:** Dual pump cascade mode control, master pump with variable speed, slave pump fixed speed (direct grid connected), including master - slave interchange, (time set by **(FA25)**)

### Controller configuration for set-point and feed-back channel (see graphic on following page)

|                                   |  |                    |
|-----------------------------------|--|--------------------|
| <b>FA01</b> PID set-point channel | Selection: 0: internal reference (value in <b>FA04</b> )<br>1: Analogue input AI1<br>2: Analogue input AI2<br>3: AI3 (Potentiometer on keypad)<br>4: Frequency (pulse input) | Default setting: 0 |
|-----------------------------------|--|--------------------|

|                                   |   |                    |
|-----------------------------------|---|--------------------|
| <b>FA02</b> PID feed-back channel | Selection: 1: Analogue input AI1<br>2: Analogue input AI2<br>3: Frequency (pulse input)<br>4: Reserved<br>5: Motor current<br>6: Output power<br>7: Output torque | Default setting: 1 |
|-----------------------------------|---|--------------------|

|   |                       |                        |
|---|-----------------------|------------------------|
| <b>FA03</b> Upper controller limit (% of set-point) | Range: 0.0...100.0 %  | Default setting: 100.0 |
| <b>FA04</b> Internal set-point value (%)            | Range: FA05....FA03 % | Default setting: 50.0  |
| <b>FA05</b> Lower controller limit (% of set-point) | Range: 0.0...100.0%   | Default setting: 0.0   |

If the controller works beyond the limits in **FA03 - FA05** inverter will be disabled and **(nP)** on display

|                                     |                                       |                    |
|-------------------------------------|---------------------------------------|--------------------|
| <b>FA06</b> PID controller polarity | Selection: 0: Positive<br>1: Negative | Default setting: 1 |
|-------------------------------------|---------------------------------------|--------------------|

|   |   |                          |
|---|---|--------------------------|
| <b>FA07</b> Automatic sleep mode                          | Selection: 0: activated<br>1: deactivated | Default setting: 1       |
| <b>FA09</b> Frequency threshold for sleep mode activation | Range: between F112...F111                | Default setting: 5.00 Hz |
| <b>FA10</b> Time delay for sleep mode activation (sec.)   | Range: 0...500 sec.                       | Default setting: 15 sec. |
| <b>FA11</b> Delay-time for restart from sleep mode        | Range: 0...3000 sec.                      | Default setting: 3.0 sec |

If the inverter runs for a programmed time, (set by **FA10**) below the minimum frequency, (set by **FA09**), it will stop and enter in sleep mode, displayed as **nP**. (feed-back value must stay within programmed limits FA03-FA04).

If feed back (pressure) falls below the value in **(FA05)**, inverter will restart again, after the delay-time in **(FA11)**

|  |                            |                        |
|--|----------------------------|------------------------|
| <b>FA12</b> Maximum working frequency in PID | Range: FA09.....Fa111 (Hz) | Default setting: 50 Hz |
|--|----------------------------|------------------------|

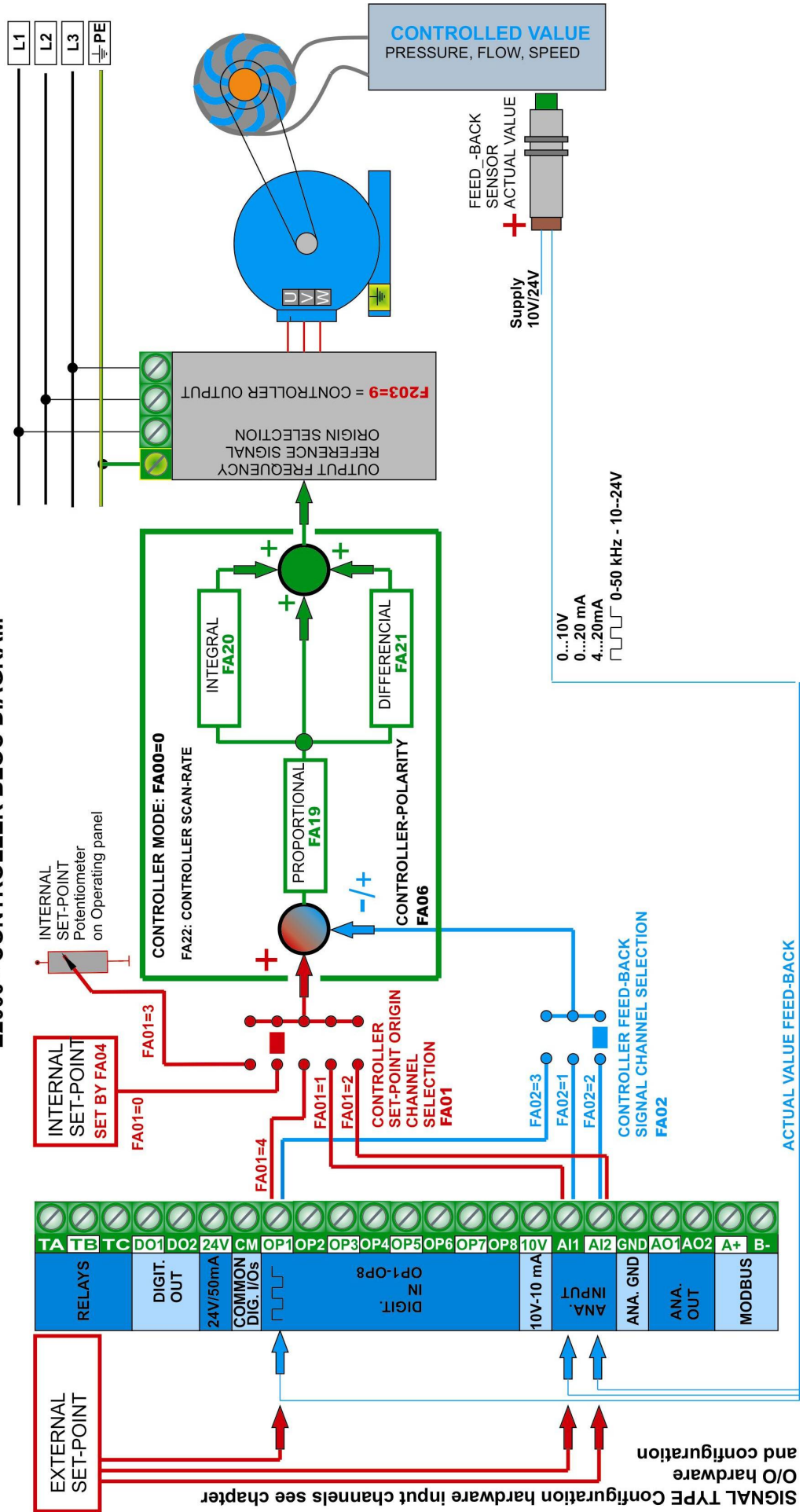
This parameter limits the maximum working frequency in PID mode

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|--|---|--------------------|
| <b>FA18</b> Variable set-point allowed | Selection: 0: deactivated<br>1: activated | Default setting: 1 |
|--|---|--------------------|

If **FA18=0:** It is not possible, to change the fixed set-point in **(FA04)** during controller operation

17) Parameter group A00: PID controller setup

E2000 - CONTROLLER BLOC DIAGRAM



### PID controller parameter setting

|  |                         |                           |
|--|-------------------------|---------------------------|
| <b>FA19</b> Proportional gain <b>P</b>               | Range: 0.00...10.00     | Default setting: 0.3      |
| <b>FA20</b> Integration time <b>I</b> (sec.)         | Range: 0.1...100.0 sec. | Default setting: 0.3 sec. |
| <b>FA21</b> Differential time <b>D</b> (sec.)        | Range: 0.00...10.00     | Default setting: 0.0 sec. |
| <b>FA22</b> Controller cycle time / scan-rate (sec.) | Range: 0.1...10.0 sec.  | Default setting: 0.1 sec. |

#### Reversing lock for negative controller results

|                            |  |                    |
|----------------------------|--|--------------------|
| <b>FA23</b> Reversing lock | Selection 0: Reversing not allowed<br>1: Reversing allowed | Default setting: 0 |
|----------------------------|--|--------------------|

### Specific pump controller parameter

Specific functions for dual pump booster station control are available in E2000+ inverters. Please ask for detailed description and configuration proposals

#### Master / Slave interchange

|   |                                   |                        |
|---|-----------------------------------|------------------------|
| <b>FA24</b> Interchange time: units                 | Selection: 0: hours<br>1: minutes | Default setting: 0     |
| <b>FA25</b> Interchange time setting (hours / min.) | 1...9999                          | Default setting: 100 h |


#### Idling / lack of water protection

|  |   |                         |
|--|---|-------------------------|
| <b>FA26</b> Lack of water protection concept                               | Selection: 0: No protection<br>1: Sensor signal through digital input<br>2: Controller algorithm<br>3: Motor idling current detection | Default setting: 0      |
| <b>FA27</b> Current limit for lack of water detection (% of rated current) | Range: 10...150 %   | Default setting: 80%    |
| <b>FA28</b> Recheck delay time (sec.)                                      | Range 0.0...3000 sec.   | Default: 60 sec.        |
| <b>FA66</b> Delay time for lack of water message (FA26=3)                  | Range: 0...60 sec.  | Default setting: 2 sec. |

**FA26=1:** Lack of water is triggered through digital input (function assignation code **30**) – it will stop the inverter and display **EP1**. The „Water OK“ signal through a different digital input (function assignation code **31**) will reset the system. FA26=1: there is no delay for fault trigger.

**FA26=2:** In case the controller reaches the maximum frequency, and the motor current still remains below the value in **FA27**, the controller will interpret the situation as lack of water. **EP2** will show up on the display. The inverter will stop immediately.

**FA26=3:** Detection via motor current measuring only. If the motor current falls below the value in **FA66**, the fault will be triggered with delay, set in **FA66**. Inverter will stop and **EP3** will show up on the display.

**FA28** Recheck time, timeframe for the inverter to recheck, if lack of water condition still persists, before it restarts. It is anytime possible to reset the system, pressing 

#### Controller dead band +/- % of the set point

|  |                     |                      |
|--|---------------------|----------------------|
| <b>FA29</b> Dead band setting (% of set-point) | Range: 0.0 - 10.0 % | Default setting: 2.0 |
|--|---------------------|----------------------|

If the feed-back (actual value) stays within the dead band, the controller does not make any activity, and it keeps the output frequency constant. The FA29 parameter is used also for starting/stopping the fixed speed pump – see below

#### Dual pump booster control (one pump inverter controlled, one pump fixed speed)

|  |                         |                       |
|--|-------------------------|-----------------------|
| <b>FA30</b> Delay-time to start inverter pump (sec.)     | Range: 2.0 - 999.9 sec. | Default setting: 20.0 |
| <b>FA31</b> Delay-time, to start fixed speed pump (sec.) | Range: 0.1 - 999.9 sec. | Default setting: 30.0 |
| <b>FA32</b> Delay-time to stop fixed speed pump (sec.)   | Range: 0.1 - 999.9 sec. | Default setting: 30.0 |

If the feed-back value (actual value) exceeds the limits, given by FA29, the fixed pump will be started or respectively stopped. Start /Stop delay time is set by **FA31** and **FA32**.

17) Parameter group A00: PID controller setup

**PID controller secondary parameter set**

|   |  |                           |
|---|--|---------------------------|
| <b>FA38</b> Proportional gain (2) <b>P</b>        | Range: 0.00...10.00  | Default setting: 0.3      |
| <b>FA39</b> Integration time (2) <b>I</b> (sec.)  | Range: 0.1...100.0 sec.  | Default setting: 0.3 sec. |
| <b>FA40</b> Differential time (2) <b>D</b> (sec.) | Range: 0.00...10.00  | Default setting: 0.0 sec. |
| <b>FA40</b> PID parameter switchover mode         | Selection:<br>0: no switchover<br>1: reserved<br>2: depending on PID deviation | Default setting: 0        |

**Reversing lock for negative controller results**

|                                    |                    |                    |
|------------------------------------|--------------------|--------------------|
| <b>FA42</b> Switchover threshold 1 | Range: FA05...FA43 | Default setting: 0 |
| <b>FA43</b> Switchover threshold 1 | Range: FA42...FA03 | Default setting: 0 |

For PID deviation below **FA42**, first PID parameter set is used, above **FA43** second PID parameter set is activated, between **FA42** and **FA 43** parameter values are interpolated.

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**Emergency functions**

|  |  |                        |
|--|--|------------------------|
| <b>FA59</b> Selection of different emergency functions | Selection: 0: no function selected<br>1: FIREMODE 1<br>2: FIREMODE 2 | Default setting: 0     |
| <b>FA60</b> Frequency for emergency condition          | Range F112...F111  | Default setting: 50 Hz |
| <b>FA58</b> Pressure for emergency conditions          | Range 0.0....100%  | Default setting: 80%   |
| <b>FA62</b> Reset options                              | Selection: 0: no RESET possible<br>1: via trigger input              | Default setting: 0     |

Emergency condition is triggered through specific terminal command (digital input - Dlx assignment code **33**) in this case, all protection functions are deactivated, and all auto-restart functions are activated.

FIREMODE 1 Inverter works with the regular set-point

FIREMODE 2, Inverter works with fixed frequency, set in parameter **FA60**

Emergency pressure mode is activated by terminal, digital input (Dlx assignment code **32**)

**FA62=0**: Inverter stays in FIREMODE, once triggered by digital input, **FA62=1**: inverter quits from FIREMODE, after trigger input is deactivated.